

Antonio Romano · Addolorata Marasco

Classical Mechanics with *Mathematica*[®]

Second Edition



Contents

Part I Introduction to Linear Algebra and Differential Geometry

1	Vector Space and Linear Maps	3
1.1	Definition of Vector Space	3
1.2	Dimension of a Vector Space	5
1.3	Basis Changes	7
1.4	Vector Subspaces	8
1.5	Algebras	9
1.6	Examples	9
1.7	Linear Maps	11
1.8	Exercises	14
2	Tensor Algebra	17
2.1	Linear Forms and Dual Vector Space	17
2.2	Biduality	20
2.3	Covariant 2-Tensors	21
2.4	(r, s) -Tensors	25
2.5	Tensor Algebra	26
2.6	Contraction and Contracted Multiplication	26
2.7	Exercises	28
3	Skew-Symmetric Tensors and Exterior Algebra	31
3.1	Skew-Symmetric $(0, 2)$ -Tensors	31
3.2	Skew-Symmetric $(0, r)$ -Tensors	35
3.3	Exterior Algebra	38
3.4	Oriented Vector Spaces	40
3.5	Exercises	41

4	Euclidean and Symplectic Vector Spaces	43
4.1	Representation Theorems for Symmetric and Skew-Symmetric (0, 2)-Tensors	43
4.2	Degenerate and Nondegenerate (0, 2)-Tensors	47
4.3	Pseudo-Euclidean Vector Spaces	50
4.4	Euclidean Vector Spaces	51
4.5	Eigenvectors of Euclidean 2-Tensors	54
4.6	Orthogonal Transformations	56
4.7	Symplectic Vector Spaces	59
4.8	Exercises	61
5	Duality and Euclidean Tensors	63
5.1	Duality	63
5.2	Euclidean Tensors	64
5.3	The Levi–Civita Tensor	65
5.4	Exercises	67
6	Differentiable Manifolds	69
6.1	Differentiable Manifolds	69
6.2	Differentiable Functions and Curves on Manifolds	73
6.3	Tangent Vector Space	74
6.4	Cotangent Vector Space	77
6.5	Differential and Codifferential of a Map	80
6.6	Tangent and Cotangent Fiber Bundles	84
6.7	Riemannian Manifolds	85
6.8	Geodesics of a Riemannian Manifold	87
6.9	Exercises	91
7	One-Parameter Groups of Diffeomorphisms	97
7.1	Global and Local One-Parameter Groups	97
7.2	Lie’s Derivative	100
7.3	Exercises	104
8	Exterior Derivative and Integration	107
8.1	Exterior Derivative	107
8.2	Closed and Exact Differential Forms	110
8.3	Properties of Exterior Derivative	111
8.4	An Introduction to the Integration of r -Forms	113
8.5	Exercises	117
9	Absolute Differential Calculus	119
9.1	Preliminary Considerations	119
9.2	Affine Connection on Manifolds	122
9.3	Parallel Transport and Autoparallel Curves	124
9.4	Covariant Differential of Tensor Fields	126

9.5	Torsion and Curvature Tensors	127
9.6	Riemannian Connection	131
9.7	Differential Operators on a Riemannian Manifold	133
9.8	Exercises	134
10	An Overview of Dynamical Systems	137
10.1	Modeling and Dynamical Systems	137
10.2	General Definitions and Cauchy's Problem	140
10.3	Preliminary Considerations About Stability	142
10.4	Definitions of Stability	144
10.5	Analysis of Stability: The Direct Method	146
10.6	Poincaré's Perturbation Method	150
10.7	Introducing the Small Parameter	153
10.8	Weierstrass' Qualitative Analysis	155
10.9	Exercises	159

Part II Mechanics

11	Kinematics of a Point Particle	163
11.1	Space–Time Frames of Reference of Classical Kinematics	163
11.2	Trajectory of a Point Particle	164
11.3	Velocity and Acceleration	165
11.4	Velocity and Acceleration in Plane Motions	167
11.5	Circular Motion and Harmonic Motion	170
11.6	Compound Motions	172
11.7	Exercises	177
12	Kinematics of Rigid Bodies	179
12.1	Change of the Frame of Reference	179
12.2	Velocity Field of a Rigid Motion	181
12.3	Translational and Rotational Motions	184
12.4	Spherical Rigid Motions	187
12.5	Rigid Planar Motions	190
12.6	Two Examples	190
12.7	Relative Motions	192
12.8	Exercises	196
13	Principles of Dynamics	199
13.1	Introduction	199
13.2	Principle of Inertia and Inertial Frames	200
13.3	Dynamical Interactions and Force Laws	201
13.4	Newton's Second Law	205
13.5	Mechanical Determinism and Galilean Relativity Principle	206
13.6	Balance Equations	207
13.7	Kinetic Energy and König's Theorem	210

13.8	Kinetic Energy Theorem	212
13.9	Dynamics in Noninertial Frames	213
13.10	Constrained Dynamics	213
13.11	Exercises	215
14	Dynamics of a Material Point	217
14.1	Central Forces	217
14.2	Newtonian Forces	221
14.3	Two-Body Problem	225
14.4	Kepler's Laws	227
14.5	Scattering by Newtonian Forces	228
14.6	Vertical Motion of a Heavy Particle in Air	230
14.7	Curvilinear Motion of a Heavy Particle in Air	233
14.8	Terrestrial Dynamics	236
14.9	Simple Pendulum	240
14.10	Rotating Simple Pendulum	242
14.11	Foucault's Pendulum	245
14.12	Exercises	248
15	General Principles of Rigid Body Dynamics	251
15.1	Mass Density and Center of Mass	251
15.2	Linear Momentum, Angular Momentum, and Kinetic Energy of a Rigid Body	252
15.3	Tensor of Inertia	254
15.4	Some Properties of the Tensor of Inertia	257
15.5	Ellipsoid of Inertia	259
15.6	Active and Reactive Forces	260
15.7	Balance Equations for a Rigid Body: Theorem of Kinetic Energy	263
15.8	Exercises	264
16	Dynamics of a Rigid Body	267
16.1	Rigid Body with a Smooth Fixed Axis	267
16.2	Compound Pendulum	269
16.3	Solid with a Fixed Point: Euler's Equations	269
16.4	Poinsot's Motions	271
16.5	Uniform Rotations	274
16.6	Poinsot's Motions in a Gyroscope	275
16.7	Heavy Gyroscope	276
16.8	Some Remarks on the Heavy Gyroscope	282
16.9	Torque of Terrestrial Fictitious Forces	285
16.10	Foucault's Gyroscope and Gyroscope Compass	287
16.11	Free Heavy Solid	290

17 Lagrangian Dynamics	293
17.1 Introduction	293
17.2 Dynamics of Constrained Systems	294
17.3 Configuration Space	295
17.4 Virtual Velocities and Nonholonomic Constraints	297
17.5 Configuration Space–Time	299
17.6 Simple Example	300
17.7 Principle of Virtual Power	302
17.8 Lagrange’s Equations	305
17.9 Conservative Forces	308
17.10 First Integrals	311
17.11 Symmetries and First Integrals	313
17.12 Lagrange’s Equations for Nonholonomic Constraints	318
17.13 Small Oscillations	320
17.14 Hamilton’s Principle	324
17.15 Geometric Formulations of Lagrangian Dynamics	328
17.16 Legendre’s Transformation	332
17.17 Exercises	336
18 Hamiltonian Dynamics	345
18.1 Symplectic Structure of the Phase Space	345
18.2 Canonical Coordinates	347
18.3 Generating Functions of Canonical Transformations	349
18.4 Isomorphism Between Vector Fields and Differential Forms	351
18.5 Global and Local Hamiltonian Vector Fields	353
18.6 Poisson Brackets	354
18.7 First Integrals and Symmetries	356
18.8 Poincaré’s Absolute and Relative Integral Invariants	359
18.9 Two Fundamental Theorems	362
18.10 Volume Form on Invariant Submanifolds	365
18.11 Time-Dependent Hamiltonian Mechanics and Contact Manifolds	368
18.12 Contact or Canonical Coordinates	370
18.13 Locally Hamiltonian Fields	373
18.14 Globally Hamiltonian Fields	376
18.15 Exercises	378
19 The Hamilton–Jacobi Theory	381
19.1 The Hamilton–Jacobi Equation	381
19.2 Separation Method	384
19.3 Examples of Separable Systems	386
19.4 Hamilton’s Principal Function	389
19.5 Time-dependent Hamilton–Jacobi Equation	396

20	Completely Integrable Systems	399
20.1	Arnold–Liouville’s Theorem	399
20.2	Angle–Action Variables	404
20.3	Fundamental Frequencies and Orbits	409
20.4	Angle–Action Variables of Harmonic Oscillator	412
20.5	Angle–Action Variables for a Material Point in Newtonian Fields	413
20.6	Bohr–Sommerfeld Quantization Rules	417
20.7	A Sketch of the Hamiltonian Perturbation Theory	419
20.8	Overview of KAM Theorem	424
21	Elements of Statistical Mechanics of Equilibrium	427
21.1	Introduction	427
21.2	Kinetic Theory of Gases	428
21.3	Boltzmann–Gibbs Distribution	433
21.4	Equipartition of Energy	437
21.5	Statistical Mechanics and Ergodic Theory	440
21.6	Fundamental Formulae Related to the Structure Function ω_E	443
21.7	Some Simple Thermodynamic Applications	448
21.8	The Theorem of Equipartition of Kinetic Energy	450
21.9	The Boltzmann Distribution	451
22	Impulsive Dynamics	457
22.1	Balance Equations of Impulsive Dynamics	457
22.2	Fundamental Problem of Impulsive Dynamics	460
22.3	Lagrangian Formulation of Impulsive Dynamics	461
22.4	Analysis of the Lagrange Equations	464
22.5	Smooth Collision of Two Solids	465
22.6	Exercises	468
23	Introduction to Fluid Mechanics	473
23.1	Kinematics of a Continuous System	473
23.2	Velocity Gradient	475
23.3	Rigid, Irrotational, and Isochoric Motions	477
23.4	Mass Conservation	479
23.5	Equations of Balance of a Perfect Fluid	480
23.6	Statics of Fluids	482
23.7	Fundamental Theorems of Fluid Dynamics	486
23.8	Boundary Value Problems for a Perfect Fluid	491
23.9	Two-Dimensional Steady Flow of a Perfect Fluid	492
23.10	D’Alembert’s Paradox and the Kutta–Joukowsky Theorem	500
23.11	Waves in Perfect Gases	502

24	An Introduction to Celestial Mechanics	505
24.1	A Brief Historical Overview of Celestial Mechanics	505
24.2	The Orbital Elements	506
24.3	Orbital Elements a , e , and E	509
24.4	Orbital Elements i , Ω , and ω	512
24.5	The Restricted Three-Body Problem	514
24.6	Equilibria of the Restricted Three-Body Problem	518
24.7	The N -Body Problem	520
24.8	Hamiltonian Form of N -Body Problem	521
24.9	Angle–Action Variables for N -Body Problem	524
24.10	Newton’s Gravitational Law	525
24.11	Newton’s Gravitation Theory for Extended Body	526
24.12	Asymptotic Behavior of Gravitational Potential	529
24.13	Local Inertial Frames and Tidal forces	531
24.14	Self-Gravitating Bodies	534
25	One-Dimensional Continuous Systems	539
25.1	The One-Dimensional Model and the Linear Mass	539
25.2	Integral and Local Laws of Balance	541
25.3	An Example: Euler’s Beam	543
25.4	Wires	545
25.5	Suspension Bridge	546
25.6	Homogeneous Catenary	548
25.7	The Vibrating String Equation	550
25.8	Boundary Value Problems and Uniqueness Theorems	551
25.9	The Method of Separated Variables	553
25.10	Eigenvalues and Eigenfunctions of Sturm–Liouville Boundary Value Problems	554
25.11	Initial Value Problems	557
25.12	Homogeneous String at Constant Tension and Fixed End Points	558
25.13	Pinched or Struck String	560
25.14	D’Alembert’s Integral	563
25.15	D’Alembert’s Solution for a String with Fixed End Points	566
26	An Introduction to Special Relativity	569
26.1	Galilean Relativity	569
26.2	Optical Isotropy Principle	572
26.3	Simple Consequences of Lorentz’s Transformations	576
26.4	Relativistic Composition of Velocities and Accelerations	578
26.5	Principle of Relativity	581
26.6	Covariance of Maxwell’s Equations	583
26.7	Relativistic Dynamics	584

26.8	Minkowski's Space-Time	587
26.9	Physical Meaning of Minkowski's Space-Time	591
26.10	Four-Dimensional Equation of Motion	593
26.11	Tensor Formulation of Electromagnetism in Vacuum	595
27	Variational Calculus with Applications	599
27.1	Lagrange's Functional Space	599
27.2	Fréchet's Differential and Gâteaux's Differential	602
27.3	Particular Cases and Examples	605
27.4	Generalization of the Above Results	607
27.5	Conditional Extrema	609
27.6	Euler's Method and Rietz Method	613
27.7	Applications to Continuum Mechanics	615
Appendix A: First-Order PDE		621
Appendix B: Fourier Series		629
References		633
Index		637